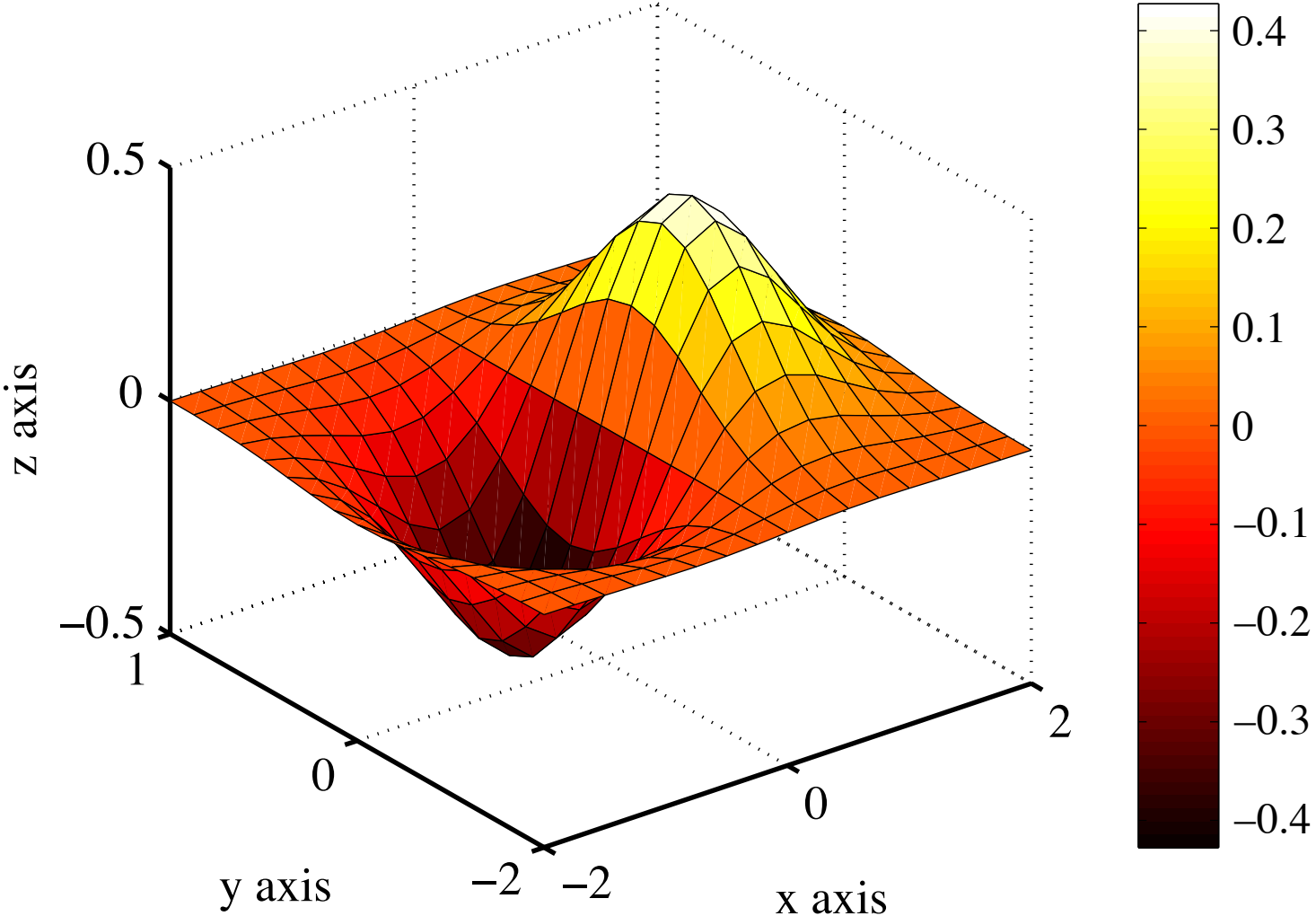
0.5
0
−0.5
z axis
1
0
−2
y axis
−2
0
2
x axis
0.4
0.3
0.2
0.1
0
−0.1
−0.2
−0.3
−0.4